

# **PART D— ACCIDENT MODIFICATION FACTORS**

## **CHAPTER 17—ROAD NETWORKS**

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## CHAPTER 17 ROAD NETWORKS

### 17.1. INTRODUCTION

Chapter 17 presents Accident Modification Factors (AMFs) applicable to planning, design, operations, education, and enforcement-related decisions that are applied holistically to a road network. From the federal level to the state and local levels, planning, engineering, and policy decisions affect the physical road network. This in turn has an impact on the mode, route, and trip choices that users make. As the pattern of trips on the network changes, the collective safety effects on the network will change. The information presented in this chapter is used to identify effects on expected average crash frequency resulting from treatments applied to road networks.

The *Part D Introduction and Applications Guidance* section provides more information about the processes used to determine the information presented in this chapter.

Chapter 17 is organized into the following sections:

- Definition, Application, and Organization of AMFs (Section 17.2);
- Crash Effects of Network Planning and Design Approaches/Elements (Section 17.3);
- Crash Effects of Network Traffic Control and Operational Elements (Section 17.4);
- Crash Effects of Road-Use Culture Network Considerations and Treatments (Section 17.5); and
- Conclusion (Section 17.6).

Appendix A presents the crash effects of treatments for which AMFs are not currently known.

### 17.2. DEFINITION, APPLICATION, AND ORGANIZATION OF AMFS

AMFs quantify the change in expected average crash frequency (crash effect) at a site caused by implementing a particular treatment (also known as a countermeasure, intervention, action, or alternative), design modification, or change in operations. AMFs are used to estimate the potential change in expected crash frequency or crash severity plus or minus a standard error due to implementing a particular action. The application of AMFs involves evaluating the expected average crash frequency with or without a particular treatment, or estimating it with one treatment versus a different treatment.

Specifically, the AMFs presented in this chapter can be used in conjunction with activities in *Chapter 6 Select Countermeasures*, and *Chapter 7 Economic Appraisal*. Some *Part D* AMFs are included in *Part C* for use in the predictive method. Other *Part D* AMFs are not presented in *Part C* but can be used in the methods to estimate change in crash frequency described in Section C.7 of the *Part C Introduction and Applications Guidance*. *Chapter 3 Fundamentals*, Section 3.5.3 Accident Modification Factors provides a comprehensive discussion of AMFs including: an introduction to AMFs, how to interpret and apply AMFs, and applying the standard error associated with AMFs.

Chapter 17 presents AMFs applicable to planning, design, operations, education, and enforcement-related decisions that are applied holistically to a road network.

Chapter 3 Fundamentals, Section 3.5.3 Accident Modification Factors provides a comprehensive discussion of AMFs.

There are three categories of treatments: an AMF is available; a trend is available but not AMF; no trend and no AMF information is available.

44 In all *Part D* chapters, the treatments are organized into one of the following  
45 categories:

- 46 1. AMF is available;
- 47 2. Sufficient information is available to present a potential trend in crashes or  
48 user behavior, but not to provide an AMF; and
- 49 3. Quantitative information is not available.

50 Treatments with AMFs (Category 1 above) are typically estimated for three  
51 accident severities: fatal, injury, and non-injury. In *Part D*, fatal and injury are  
52 generally combined and noted as injury. Where distinct AMFs are available for fatal  
53 and injury severities, they are presented separately. Non-injury severity is also  
54 known as property-damage-only severity.

55 Treatments for which AMFs are not presented (Categories 2 and 3 above)  
56 indicate that quantitative information currently available did not meet the criteria for  
57 inclusion in the HSM. The absence of an AMF indicates additional research is needed  
58 to reach a level of statistical reliability and stability to meet the criteria set forth  
59 within the HSM. Treatments for which AMFs are not presented are discussed in  
60 Appendix A.

### 61 **17.3. CRASH EFFECTS OF NETWORK PLANNING AND DESIGN** 62 **APPROACHES/ELEMENTS**

#### 63 **17.3.1. Background and Availability of AMFs**

64 This section presents general background information about the crash effects of  
65 network planning and design approaches/elements. Planning decisions include a  
66 range of issues that may affect the expected average crash frequency on the road  
67 network. Examples of planning decisions that affect network safety include:

- 68 ■ The travel frequencies and travel distances in the course of people's daily  
69 activities;
- 70 ■ The travel mode used (train, subway, bus, car, bicycle or walking);
- 71 ■ The period of greatest travel demand (throughout the day, week, and year);
- 72 ■ The facility type used (whether people travel on a freeway or an arterial  
73 road);
- 74 ■ The number of high-traffic volume or low-traffic volume intersections that  
75 road-users must pass through;
- 76 ■ The distance between access points;
- 77 ■ The need for children to cross roads on their way to school; and,
- 78 ■ The operating speeds implied by the local residential road network (e.g.,  
79 straight wide roadways, narrow curved roads, or cul-de-sacs).

80 Similar to planning decisions, design and operational decisions vary in their  
81 impact on the network. Decisions to widen a shoulder or to provide a turn lane may  
82 have little effect on travel patterns over the network as a whole. Other design and  
83 operational decisions may affect a wider part of the network. For example, one-way

84 street systems appear to affect a relatively limited area, but may have crash  
85 implications for other streets in the road network due to changes in traffic patterns.

86 Network design elements include treatments and broader design concepts  
87 intended to achieve uniformity and similarities across a roadway network. Self-  
88 explaining roads and transportation safety planning (TSP) are two examples of  
89 design principles that are applied across a network to achieve geometric and  
90 operational characteristics aimed at reducing crashes. Self-explaining roads are  
91 designed to make the function and role of a road immediately clear, recognizable,  
92 and self-enforcing. Design stimulates drivers to adapt and reduce speed.  
93 Transportation safety planning involves explicitly, proactively, and comprehensively  
94 implementing measures known to reduce expected average crash frequency.

95 Exhibit 17-1 summarizes the treatments related to network planning and design  
96 approaches and elements. There are currently no AMFs for these treatments.  
97 Appendix A presents general information and potential trends in crashes and user  
98 behavior for these treatments.

99 **Exhibit 17-1: Treatments Related to Network Planning and Design Approaches/Elements**

HSM Section	Treatment	Urban	Suburban	Rural
Appendix A	Apply elements of self-explaining roadway design	T	T	T
Appendix A	Apply elements of transportation safety planning in transportation network design	T	T	T

100 NOTE: T = Indicates that an AMF is not available but a trend regarding the potential change in crashes or user  
101 behavior is known and presented in Appendix A.

There are no treatments related to network planning and design with AMFs.

102 **17.4. CRASH EFFECTS OF NETWORK TRAFFIC CONTROL AND**  
103 **OPERATIONAL ELEMENTS**

104 **17.4.1. Background and Availability of AMFs**

105 The material presented in this section focuses on treatments related to traffic  
106 control and operational elements that are applied across a network or sub-area.  
107 Network traffic control and operational elements include treatments such as area-  
108 wide traffic calming, creating a network of one-way couplets, or implementing a  
109 specific level of access management across a set of facility types within a network.

110 Exhibit 17-2 summarizes treatments related to network traffic control and  
111 operational elements and the corresponding AMFs available.

112 **Exhibit 17-2: Treatments Related to Network Traffic Control and Operational Elements**

HSM Section	Treatment	Urban	Suburban	Rural
17.4.2.1	Implement Area-Wide Traffic Calming	✓	-	-
Appendix A	Convert two-way streets to one-way streets	T	T	T
Appendix A	Convert one-way streets to two-lane, two-way streets	T	T	T
Appendix A	Modify the level of access control on transportation network	T	-	-

113 NOTE: ✓ = Indicates that an AMF is available for the treatment.  
114 T = Indicates that an AMF is not available but a trend regarding the potential change in crashes or user  
115 behavior is known and presented in Appendix A.  
116 - = Indicates that an AMF is not available and a trends is not known.

AMFs related to traffic calming are summarized in Section 17.4.2.

117 **17.4.2. Network Traffic Control and Operations Treatments with AMFs**

118 **17.4.2.1. Implement Area-Wide Traffic Calming**

119 The main purpose of traffic calming is to reduce traffic volumes and operating  
 120 speeds on residential local roads. The traditional approach to traffic calming is  
 121 known as Level I Traffic Calming.<sup>(11)</sup> In Level I Traffic Calming, various site-specific  
 122 calming techniques are applied to a local street network, usually a residential area.

123 Numerous traffic calming measures can be used to reduce traffic volume and  
 124 driving speed on an area-wide basis. Most measures focus on managing vehicles  
 125 through physical or operational devices such as: vehicle restrictions, lane narrowing,  
 126 traffic circles, speed humps, raised crosswalks, chicanes, rumble strips, pavement  
 127 treatments, etc. Traffic calming is one application of the “self-explaining road”  
 128 approach. The measures that are implemented are designed to lead drivers to reduce  
 129 speed and to adapt their driving appropriately. Before implementing traffic calming,  
 130 the effects on pedestrians (including those with disabilities who may rely on  
 131 paratransit), cyclists, emergency services vehicles, and transit may be considered.

132 The potential crash effects of applying area-wide or corridor-specific traffic  
 133 calming measures to urban local roads, while adjacent collector roads remain  
 134 untreated are shown in Exhibit 17-3.<sup>(2,4,6)</sup> These AMFs are not applicable to fatal  
 135 accidents. The potential crash effects to non-injury crash frequency are also shown in  
 136 Exhibit 17-3. The base condition of the AMFs (i.e., the condition in which the AMF =  
 137 1.00) is the absence of area-wide traffic calming.

138 The potential crash effects of specific traffic calming measures are provided in  
 139 *Chapters 13 and 14.*

140 **Exhibit 17-3: Potential Crash Effects of Applying Area-Wide or Corridor-Specific Traffic**  
 141 **Calming to Urban Local Roads while Adjacent Collector Roads Remain**  
 142 **Untreated<sup>(2,4,6)</sup> (injury excludes fatal crashes in this exhibit)**

Treatment	Setting (Road type)	Traffic Volume AADT (veh/day)	Accident type (Severity)	AMF	Std. Error
Area-wide or corridor-specific traffic calming	Urban (All area-wide roads)	< 2,000 to 30,000	All types (Injury)	<b>0.89</b>	<b>0.1</b>
			All types (Non-injury)	<i>0.95*</i>	<i>0.2</i>
	Urban (Two-lane Local roads)	< 2,000	All types (Injury)	<b>0.82</b>	<b>0.1</b>
			All types (Non-injury)	<b>0.94*</b>	<b>0.1</b>
	Urban (Two-lane or Multilane Collector roads)	5,000 to 30,000	All types (Injury)	<b>0.94*</b>	<b>0.1</b>
			All types (Non-injury)	<i>0.97*</i>	<i>0.2</i>

Base Condition: Absence of area-wide traffic calming.

143 NOTE: Injury excludes fatal accidents in this exhibit  
 144 **Bold** text is used for the most statistically reliable AMFs. These AMFs have a standard error of 0.1 or less.  
 145 *Italic* text is used for less statistically reliable AMFs. These AMFs have standard errors between 0.2 to 0.3.  
 146 \* Observed variability suggests that this treatment could result in an increase, decrease or no change in  
 147 expected average crash frequency. See *Part D Introduction and Applications Guidance*



148 **17.5. CRASH EFFECTS OF ELEMENTS OF ROAD-USE CULTURE**  
149 **NETWORK CONSIDERATIONS**

150 **17.5.1. Background and Availability of AMFs**

151 National policy leads transportation authorities to work to improve safety by  
152 going beyond engineering-based strategies. Transportation authorities, in  
153 partnership with related organizations, seek ways to incorporate education,  
154 enforcement, and emergency services strategies into their goal for a safer  
155 transportation network. These strategies can potentially influence road-use culture  
156 and may be designed to create a safer road-use culture. Engineering and planning  
157 decisions create and shape the transportation network, and clearly affect the safety of  
158 the transportation network. The road-use culture of the people using the network  
159 also affects the safety of the transportation network.

160 This HSM section discusses road-use culture and how expected average crash  
161 frequency may be reduced by understanding how road-use culture responds to  
162 engineering, enforcement, and education.

163 Road-use culture involves each individual road user's choices, and the attitudes  
164 of society as a whole towards transportation safety. The choices made by each  
165 individual road user flow from the beliefs, values, and ideas that each road user  
166 brings to the road. The attitudes of society as a whole towards transportation safety  
167 flow from the social norms regarding acceptable behaviors on the road, and from  
168 society's decisions regarding acceptable regulation, legislation, and enforcement  
169 levels. Road-use culture evolves as individuals influence society, and society  
170 influences individuals. Additional information regarding road-use culture can be  
171 found in Appendix A.

172 Exhibit 17-4 summarizes treatments related to road use culture and the  
173 corresponding AMFs available. The treatments summarized below encompass  
174 engineering, enforcement, and education.

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AMFs and trends related to road use culture considerations are summarized in section 17.5.2 and Appendix A.

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**Exhibit 17-4: Road-Use Culture Network Considerations and Treatments**

HSM Section	Treatment	Urban	Suburban	Rural
17.5.2.1	Install automated speed enforcement	✓	-	✓
17.5.2.2	Install changeable speed warning signs	✓	✓	✓
Appendix	Deploy mobile patrol vehicles	T	T	T
Appendix	Deploy stationary patrol vehicles	T	T	T
Appendix	Deploy aerial enforcement	T	T	T
Appendix	Deploy radar and laser speed monitoring equipment	T	T	T
Appendix	Install drone radar	T	T	T
Appendix	Modify posted speed limit	T	T	T
Appendix	Conduct enforcement to reduce red-light running	T	T	T
Appendix	Conduct enforcement to reduce impaired driving	T	T	T
Appendix	Conduct enforcement to increase seat belt and helmet use	T	T	T
Appendix	Implement network-wide engineering consistency	T	T	T
Appendix	Mitigate aggressive driving through engineering	T	T	T
Appendix	Conduct public education campaigns	T	T	T
Appendix	Implement young drivers and graduated driver licensing programs	T	T	T
Appendix	Implement older driver education and retesting programs	T	T	T

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NOTE: ✓ = Indicates that an AMF is available for the treatment.  
 T = Indicates that an AMF is not available but a trend regarding the potential change in crashes or user behavior is known and presented in Appendix A.  
 - = Indicates that an AMF is not available and a trends is not known.

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**17.5.2. Road Use Culture Network Consideration Treatments with AMFs**

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**17.5.2.1. Install Automated Speed Enforcement**

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Automated enforcement systems use video or photographic identification in conjunction with radar or lasers to detect speeding drivers. The systems automatically record vehicle registrations without having to have police officers at the scene.

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The crash effects of installing automated speed enforcement in urban or rural areas on all road types are shown in Exhibit 17-5.<sup>(1,3,5,7,9,12)</sup> The base condition for this AMF (i.e., the condition in which the AMF = 1.00) is the absence of automated speed enforcement.

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206 **Exhibit 17-5: Potential Crash Effects of Automated Speed Enforcement** <sup>(1,3,5,7,9,12)</sup>

Treatment	Setting (Road type)	Traffic Volume	Accident type (Severity)	AMF	Std. Error
Install automated speed enforcement	All settings (All types)	Unspecified	All types (Injury)	<b>0.83<sup>+</sup></b>	<b>0.01</b>

Base Condition: No automated speed enforcement.

207 NOTE: **Bold** text is used for the most statistically reliable AMFs. These AMFs have a standard error of 0.1 or less.  
 208 + Combined AMF, see *Part D Applications Guidance*.

209  
 210 Multiyear programs indicate operating speeds dropped substantially at sites  
 211 with fixed cameras compared to sites with mobile cameras.<sup>(8)</sup> However, the  
 212 magnitude of the crash effect of mobile versus fixed camera sites is not certain at this  
 213 time.

214 Some speed enforcement approaches are known to have spillover effects across  
 215 the network. For example, speed cameras may affect behavior at locations not  
 216 equipped with the cameras. The publicity and public interest accompanying  
 217 installation of the cameras may lead to a generalized change in driver behavior at  
 218 locations with and without cameras.<sup>(10)</sup> Some enforcement approaches may also have  
 219 “time halo” effects. For example, the effect of operating speeds being enforced for a  
 220 specific period may remain after the enforcement is withdrawn.

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 222 The gray box below illustrates how to apply the information in Exhibit 17-5 to  
 223 calculate the crash effects of installing automated speed enforcement.

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### Effectiveness of Installing Automated Speed Enforcement

#### Question:

As part of an overall change to speed enforcement policy and an evolving safety culture, a local jurisdiction is proposing the implementation of automated speed enforcement on an urban arterial. What will be the likely reduction in the expected average crash frequency?

#### Given Information:

- Existing roadway = urban arterial
- Expected average crash frequency without treatment (See *Part C* Predictive Method) = 10 crashes/year

#### Find:

- Expected average crash frequency with installation of automated speed enforcement
- Change in expected average crash frequency

#### Answer:

- 1) Identify the Applicable AMF

AMF = 0.83 (Exhibit 17-5)

- 2) Calculate the 95<sup>th</sup> percentile confidence interval estimation of crashes with the treatment

=  $(0.83 \pm 2 \times 0.01) \times (10 \text{ crashes/year}) = 8.1 \text{ or } 8.5 \text{ crashes/year}$

The multiplication of the standard error by 2 yields a 95% probability that the true value is between 8.1 and 8.5 crashes/year. See Section 3.5.3 in Chapter 3 Fundamentals for a detailed explanation.

- 3) Calculate the difference between the expected number of crashes without the treatment and the expected number of crashes with the treatment.

#### Change in Expected Average Crash Frequency:

**Low Estimate = 10 - 8.5 = 1.5 crashes/year reduction**

**High Estimate = 10 - 8.1 = 1.9 crashes/year reduction**

- 4) **Discussion: The implementation of automated speed enforcement may potentially cause a reduction or 1.5 to 1.9 crashes/year.**

#### 17.5.2.2. Install Changeable Speed Warning Signs

Individual changeable speed warning signs give individual drivers real-time feedback regarding their speed.<sup>(7)</sup> The potential crash effects of installing these warning signs are shown in Exhibit 17-6. The base condition for this AMF (i.e., the condition in which the AMF = 1.00) is the absence of changeable speed warning signs.

278 **Exhibit 17-6: Potential Crash Effects of Installing Changeable Speed Warning Signs**  
 279 **for Individual Drivers<sup>(2)</sup>**

Treatment	Setting (Road type)	Traffic Volume	Accident type (Severity)	AMF	Std. Error
Install changeable speed warning signs for individual drivers	Unspecified (Unspecified)	Unspecified	All types (All severities)	<i>0.54</i>	<i>0.2</i>

Base Condition: Absence of changeable speed warning signs

280 NOTE: Based on international study: Van Houten and Nau 1981  
 281 *Italic* text is used for less statistically reliable AMFs. These AMFs have standard errors between 0.2 to 0.3.  
 282 Collective changeable speed warning signs give information such as the percentage of road users  
 283 exceeding the speed limit.

284 **17.6. CONCLUSION**

285 The material in this chapter focuses on the potential crash effects of treatments  
 286 that are applicable on a network-wide basis. The information presented is the AMFs  
 287 known to a degree of statistical stability and reliability for inclusion in this edition of  
 288 the HSM. Additional qualitative information regarding potential network wide  
 289 treatments is contained in Appendix A.

290 Other chapters in *Part D* present treatments related to specific site types such as  
 291 roadway segments and intersections. The material in this chapter can be used in  
 292 conjunction with activities in *Chapter 6 Select Countermeasures*, and *Chapter 7 Economic*  
 293 *Appraisal*. Some *Part D* AMFs are included in *Part C* for use in the predictive method.  
 294 Other *Part D* AMFs are not presented in *Part C* but can be used in the methods to  
 295 estimate change in crash frequency described in Section C.7 of the *Part C Introduction*  
 296 *and Applications Guidance*.

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## 332 APPENDIX A

### 333 A.1 INTRODUCTION

334 The appendix presents general information, trends in crashes and/or user-  
335 behavior as a result of the treatments, and a list of related treatments for which  
336 information is not currently available. Where AMFs are available, a more detailed  
337 discussion can be found within the chapter body. The absence of an AMF indicates  
338 that at the time this edition of the HSM was developed, completed research had not  
339 developed statistically reliable and/or stable AMFs that passed the screening test for  
340 inclusion in the HSM. Trends in crashes and user behavior that are either known or  
341 appear to be present are summarized in this appendix.

342 This appendix is organized into the following sections:

- 343 ■ Network Planning and Design Approaches/Elements (Section A.2)
- 344 ■ Network Traffic Control and Operational Elements (Section A.3)
- 345 ■ Road-Use Culture Network Considerations and Treatments (Section A.4)
- 346 ■ Catalogue of Treatments with Unknown Crash Effects (Section A.5)

### 347 A.2 NETWORK PLANNING AND DESIGN APPROACHES/ELEMENTS

#### 348 A.2.1 General Information

349 Practitioners have opportunities to consider safety at every stage and level of  
350 transportation planning and the corresponding early stages of design. By striving to  
351 construct roadways that are as safe as possible, and by explicitly incorporating safety  
352 considerations into the planning and design stages, practitioners can minimize the  
353 need for crash mitigation after construction.

#### 354 A.2.2 Trends in Crashes or User Behavior for Treatments with no 355 AMFs

##### 356 A.2.2.1 *Apply Elements of Self-Explaining Roadway Design*

357 Self-explaining roads convey a clear, simple and consistent message about the  
358 road's function and role. The message is embedded in the design and appearance of  
359 the road, using a limited number of design options and traffic control devices based  
360 on the road class. Self-explaining roads are designed to reduce driver errors and  
361 crashes. The first self-explaining roads were introduced in Holland in the 1990s.<sup>(21)</sup>

362 Drivers respond to the roadway design by adapting their driving and adjusting  
363 their speed. The cues may be physical and/or perceptual. For example, residential  
364 streets that are short and narrow create a sense of spatial enclosure which encourages  
365 drivers to slow down. Road surfaces that are color coded (e.g., to show bicycle lanes)  
366 convey information about how road users should use the space within the roadway.  
367 On self-explaining roads, drivers, pedestrians, and cyclists readily recognize and  
368 understand the relationship between the road, the adjacent land use, and  
369 environment, and the appropriate road-user response.

370 ***Classification of self-explaining roads***

371 Different road functionality requires different self-explaining design techniques.  
 372 Self-explaining roads are most relevant to local planning. Three levels of functionality  
 373 classification are suggested for self-explaining roads:<sup>(25)</sup>

- 374 1. Roads with a through function;  
 375 2. Roads with a distributor function; and,  
 376 3. Roads with an access function (residential streets).

377 Each road category is designed to match the road's function and desired  
 378 operating speed. For example, access to homes, schools, and offices is provided from  
 379 residential and distributor roads. The self-explaining approach is intended to prevent  
 380 through motorists from encroaching on residential streets. This approach appears to  
 381 reduce traffic volumes and crash rates on residential streets.<sup>(3)</sup>

382 ***Self-explaining roads in residential areas***

383 The design of self-explaining roads in residential areas stimulates drivers to be  
 384 aware that they have left the network of arterials and collectors and must reduce  
 385 their speed. The design also leads drivers to expect to encounter children,  
 386 pedestrians, and bicyclists. The low speeds of self-explaining roads are particularly  
 387 important for pedestrian and child safety. Children are highly vulnerable to speeding  
 388 traffic because they are often impulsive and lack the experience and judgment  
 389 necessary to assess traffic conditions.

390 Lower driving speeds and increased driver expectation potentially mitigate some  
 391 of the factors that are known to contribute to pedestrian crashes. These factors  
 392 include:<sup>(9,15)</sup>

- 393 ■ Improper crossing of the roadway or intersection;  
 394 ■ Walking or playing in the roadway;  
 395 ■ Restricted sight lines;  
 396 ■ Limited time for drivers to respond to unanticipated pedestrian movements;  
 397 ■ Inadequate searching and checking by pedestrians and drivers, especially  
 398 when the vehicle is turning;  
 399 ■ Speeding; and,  
 400 ■ Pedestrians assuming that they are more visible than they actually are.

401 Self-explaining roads are generally designed to reduce operating speeds to about  
 402 18 mph in the zones where the roads are introduced. The roads are also designed to  
 403 minimize the speed differential among different road users.

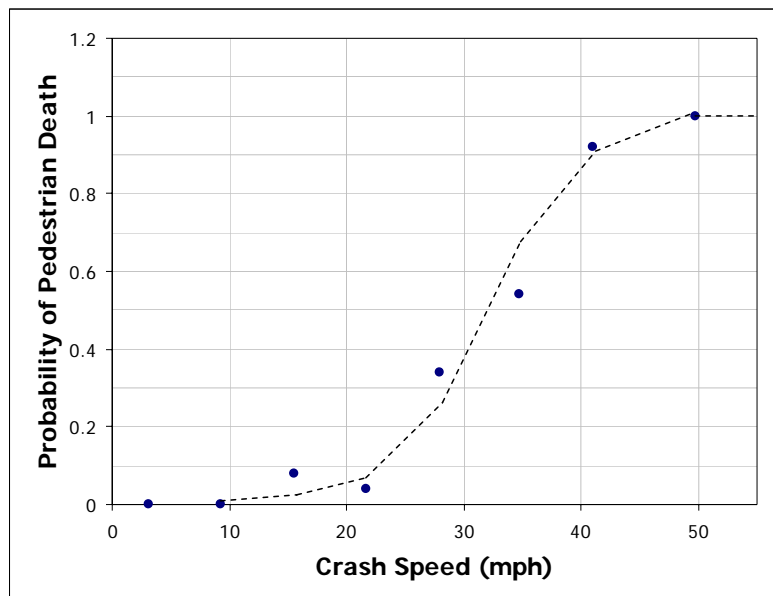
404 A study of the crash effects of self-explaining roads in Holland found that:<sup>(25)</sup>

- 405 ■ The number of fatalities declined; and,  
 406 ■ The vast majority of local residents were satisfied with the creation of an 18-  
 407 mph zone.

408 Exhibit 17-7 shows how the relationship between crash speed and the probability  
 409 of a pedestrian fatality rises rapidly when the crash speed exceeds about 18 mph.<sup>(17)</sup>



410 **Exhibit 17-7: Relationship between Crash Speed and the Probability of a Pedestrian**  
 411 **Fatality<sup>(17)</sup>**



412  
 413 Self-explaining roads appear to reduce crashes when applied in planning and  
 414 design. However, the magnitude of the crash effect is not certain at this time. More  
 415 specifically, it appears that crashes are reduced in residential areas planned with self-  
 416 explaining roads principles compared to other residential areas planned with more  
 417 traditional principles.<sup>(11)</sup> Streets with no exit, such as cul-du-sacs, appear to be  
 418 substantially safer for pedestrians, especially children when compared to other street  
 419 layouts.<sup>(11)</sup> However, the magnitude of the crash effect is not certain at this time.

420 **A.2.2.2 Apply Elements of Transportation Safety Planning in Transportation**  
 421 **Network Design**

422 Transportation Safety Planning (TSP) is a comprehensive, system-wide, proactive  
 423 process that integrates safety into transportation decision making. TSP applies to all  
 424 transportation modes and all network levels (i.e., local, regional, and state). TSP aims  
 425 to create safety planning procedures that are explicit and measurable. TSP also aims  
 426 to reduce accidents by establishing inherently safe transportation networks. On an  
 427 inherently safe transportation network, a driver is less likely to be involved in a  
 428 crash.<sup>(26)</sup>

429 TSP elements appear to improve safety when applied in planning and design.  
 430 However, the magnitude of the crash effect is not certain at this time. More  
 431 specifically, it appears that crashes are reduced in residential areas planned with TSP  
 432 principles compared to other residential areas planned with more traditional  
 433 principles.<sup>(11)</sup> Streets with no exit, such as cul-de-sacs, appear to be substantially safer  
 434 for pedestrians, especially children when compared to other street layouts.<sup>(11)</sup>  
 435 However, the magnitude of the crash effect is not certain at this time.

The following websites provide information on the latest TSP strategies and tools:

<http://www.fhwa.dot.gov/planning/SCP/>; and,

<http://tsp.trb.org/>.

**A.3 NETWORK TRAFFIC CONTROL AND OPERATIONAL ELEMENTS****A.3.1 Trends in Crashes or User Behavior for Treatments with no AMFs****A.3.1.1 Convert Two-Way Streets to One-Way Streets**

One-way operations may apply to a whole area or to only a few streets, and may be found in both downtown and residential areas. One-way streets, usually implemented to increase traffic capacity, appear to reduce crashes under certain conditions.<sup>(11)</sup>

Implementing or removing one-way systems require careful thought and attention in their planning, design, and implementation. Detailed design considerations include the geometrics in the transition to and from one-way and two-way segments, appropriate regulatory signs, pavement markings, and providing suitable accommodation for turning movements at the beginning and end of one-way segments.<sup>(11)</sup> A consideration is the effect the one-way operations may have on the surrounding road network with the intent of avoiding the transfer of crashes to a neighboring area.

One-way systems have potential operational benefits which appear to reduce crashes. The potential benefits include:

- Elimination of two-way traffic conflicts;
- Reduction in the large number of potential conflicts at intersections in a two-way system, including the elimination of left turns by opposing traffic;
- Possible reduction in waiting times for pedestrians at signals;
- Simplification of intersection traffic control; and,
- Improved traffic signal synchronization. Platoons of traffic moving at the appropriate speed may travel the length of the street with few or no stops.

Converting two-way streets to one-way streets appears to reduce head-on and left-turn accidents.<sup>(11,19)</sup> However, the magnitude of the crash effect is not certain at this time.

Potential operational and safety concerns with one-way systems include increased vehicle speed and longer trips for drivers who travel one or more blocks out of their way to reach their destinations. Constraints to emergency vehicle operations are an additional consideration for one-way street systems.

**A.3.1.2 Convert One-Way Streets to Two-Lane, Two-Way Streets**

One-way operations may apply to a whole area or to only a few streets, and may be found in both downtown and residential areas. One-way streets, usually implemented to increase traffic capacity, appear to reduce crashes under certain conditions.<sup>(11)</sup>

In a study focusing on a pair of one-way streets that passed through a business district and a residential area, the design for converting the one-way streets to two-lane, two-way streets included bicycle lanes, all-day parallel parking, wider sidewalks, and new trees and benches in the business district. “Zebra” crosswalk markings with pedestrian warning signs were added to the two intersections closest

478 to the school.<sup>(2)</sup> The study results showed that average speeds changed from 35 mph  
479 to about 25 mph. Travel times for car commuters increased slightly, and the number  
480 of bicyclists and pedestrians increased. Some vehicular traffic was diverted to  
481 alternate routes. <sup>(2)</sup>

#### 482 **A.3.1.3 Modify the Level of Access Control**

483 The safety of an access point is influenced by broad characteristics such as road  
484 class and environment, the average density of access points, and median presence on  
485 the roadway. The safety of an access point is also influenced by specific  
486 characteristics related to detailed design and traffic control devices. These  
487 characteristics include alignment with opposite driveways, proximity to  
488 intersections, permitted entry/exit movements, storage, sight triangles, etc. Changing  
489 an access and incorporating that decision into a broader access management plan or  
490 policy means the change in one access is considered in an area-wide context. The  
491 purpose of this network perspective is to minimize the likelihood that a safety  
492 concern is transferred from one location to another.<sup>(12)</sup>

493 The following levels of access may be used on urban roadways:<sup>(6)</sup>

- 494 ■ Minimal access control: high density of intersecting streets, driveways, and  
495 median openings;
- 496 ■ Moderate level of access control: frontage roads running parallel with the  
497 main roadway segment and fewer cross streets; and,
- 498 ■ High level of access control: few driveways, cross streets or median  
499 openings.

500 The high level of access control has the fewest access points. On urban roadways,  
501 a high level of access control appears to reduce injury and non-injury accidents, and  
502 may also reduce angle and sideswipe accidents at intersections and mid-block  
503 areas.<sup>(6)</sup> However, the magnitude of the crash effect is not certain at this time.

### 504 **A.4 ELEMENTS OF ROAD-USE CULTURE NETWORK** 505 **CONSIDERATIONS**

#### 506 **General Information**

507 Road-use culture affects every aspect of driving behavior. Examples include  
508 driving above the speed limit, responses to red-light cameras at intersections,  
509 behavior at all-way stops, and attitudes towards pedestrians and bicyclists.  
510 Pedestrians and bicyclists use the transportation network in accordance with their  
511 road-use culture and perception of how to respond to the network and to other road  
512 users.

513 While road users' choices may not be fully understood, it is likely that the  
514 general level of patience and politeness, or of impatience and aggression, may vary  
515 over time and from place to place. Road-use culture is also affected by familiarity  
516 with surroundings.

517 Factors such as enforcement level and the efficiency of the supporting judicial  
518 system play a role in defining road-use culture. If drivers know that speeding tickets  
519 are unlikely to be processed or that speed limits are rarely enforced, drivers will see  
520 little reason to reduce their speed.

**521 Road-Use Culture Development**

522 The way in which road-use culture develops is not well known. It appears that  
523 visible behaviors such as seat belt usage, speeding, stopping at stop signs, etc.,  
524 whether desirable or undesirable, spread more quickly than invisible behaviors, such  
525 as impaired driving.<sup>(27)</sup>

526 It also appears that conspicuous behaviors associated with a negative driving  
527 culture spread very quickly. Examples of these behaviors include parking on the  
528 wrong side of the street, “cutting off” another driver, making threatening gestures, or  
529 not signaling.<sup>(27)</sup>

530 Studies suggest that it is particularly difficult to change road-use culture  
531 regarding driving speed and observing speed limits. Progress has been made in  
532 changing road-use culture regarding driving under the influence (DUI) and seat belt  
533 usage. Programs and procedures targeted at young drivers, such as Graduated  
534 Driver’s License (GDL), and at older drivers aim to reduce the accident rates of these  
535 two vulnerable groups. Studies show that enforcement can change driver behavior, if  
536 only in the short term. Automated enforcement for speed and red-light-running,  
537 combined with appropriate enabling legislation, offers the potential to reduce  
538 crashes.

**539 Road Use Culture and Traffic Enforcement**

540 Acceptable driving speed is one of the most important “norms” that helps to  
541 define a driving culture. For example, driving 5 to 10 mph greater than the posted  
542 speed limit may be culturally acceptable and considered the norm. Being aware of  
543 the norm, a driver who notices that a driver ahead is slowing down to the speed limit  
544 or to below the speed limit will likely respond in an appropriate way.

545 Drivers who do not conform to the norm for driving behavior, or who are  
546 driving in unfamiliar surroundings where the prevailing road-use culture differs  
547 from their own, may be more likely to have an accident than drivers who are familiar  
548 with the local road-use culture and conform to it. Drivers often choose to exceed the  
549 posted speed limit. This choice is an important safety issue because the risk may  
550 increase as operating speeds increase.<sup>(20)</sup>

551 Most drivers underestimate their driving speed, especially when driving fast.  
552 After a high-speed period, drivers who slow down typically perceive their new speed  
553 as less than it actually is. In addition, perceptual limitations to geometric features  
554 such as curvature can lead to drivers failing to respond appropriately to curvature.<sup>(20)</sup>

555 As most enforcement interventions appear to have little effect on modifying  
556 road-use culture, it is generally accepted that speed limits need to be self-enforcing. If  
557 drivers believe that speed limits are unreasonable, inappropriate, or inconsistently  
558 applied to the network, it is very unlikely that temporary enforcement measures can  
559 reduce speeds permanently.

**560 Summary**

561 Design of treatments and interventions that change driver behavior and result in  
562 crash reductions can be more successful through a better understanding of driver  
563 culture. An improved understanding of driver culture will also help contribute to  
564 increasingly effective safety campaigns and enforcement procedures.

565 **A.4.1 Trends in Crashes or User Behavior for Treatments with no**  
566 **AMFs**

567 **A.4.1.1 Deploy Mobile Patrol Vehicles**

568 Mobile patrol vehicles act as a speeding deterrent, but compliance with speed  
569 limits has been shown to decline with distance from the patrol vehicles.<sup>(20)</sup> The  
570 visibility of the patrol vehicle is important. It has been shown that when overhead  
571 lights were removed from patrol cars, mobile patrols ticketed 25% more motorists  
572 than when the patrol cars retained their overhead lights.<sup>(20)</sup>

573 The time halo effect of mobile patrol vehicles has been found to last from an hour  
574 to 8 weeks depending on the length and frequency of the deployments.<sup>(20)</sup>

575 **A.4.1.2 Deploy Stationary Patrol Vehicles**

576 Stationary patrol vehicles have been shown to lead to “a pronounced decrease in  
577 average traffic speed.”<sup>(20)</sup>

578 **A.4.1.3 Deploy Aerial Enforcement**

579 Aerial speed enforcement has reduced vehicle crashes in Australia.<sup>(20)</sup> In New  
580 York, aerial enforcement was used successfully to apprehend drivers who used radar  
581 detectors and CB radio to avoid being caught speeding.<sup>(20)</sup>

582 **A.4.1.4 Deploy Radar and Laser Speed Monitoring Equipment**

583 Laser speed monitoring equipment can be used to apprehend drivers whose cars  
584 have radar detectors. These drivers tend to travel at the most extreme speeds.<sup>(20)</sup>

585 **A.4.1.5 Install Drone Radar**

586 Drone radars, or unattended radar transmitters, have been shown to slightly  
587 reduce average vehicle speed, and to decrease by 30 to 50% the number of drivers  
588 who exceed the speed limit by more than 10 mph.<sup>(20)</sup>

589 **A.4.1.6 Modify Posted Speed Limit**

590 Drivers tend to drive at the speed that they find acceptable and safe, despite  
591 posted speed limits.

592 Little or no effect on operating speed has been found for low- and moderate-  
593 speed roads where posted speed limits were changed (raised or lowered).<sup>(20)</sup> On high-  
594 speed roads such as freeways, “studies in the USA and abroad generally show an  
595 increase in speeds when speed limits are raised.”<sup>(20)</sup>

596 The net crash effect of speed limits and changes in speed limits across the  
597 transportation network is not fully known. More information is needed to  
598 understand how drivers respond to speed limits and how driver behavior can be  
599 modified. This information would help to improve how speed limits are set, and  
600 would help to maximize the results of speed enforcement efforts.

601 **A.4.1.7 Conduct Enforcement to Reduce Impaired Driving**

602 Although alcohol and drugs have a major effect on driver error, and although  
603 driving under the influence (DUI) of alcohol or other drugs is widely regarded as a  
604 major problem, attitudes towards drinking and driving are not fully understood.

605 Behavioral controls appear to provide the best results for reducing drunk driving  
606 among people with multiple DUI offenses.<sup>(8)</sup> Behavioral controls include internal  
607 behavior controls such as moral beliefs concerning alcohol-impaired driving, and  
608 external behavioral controls such as the offenders' perceptions of accidents and  
609 criminal punishment. Social controls or peer group pressure appear to be less  
610 effective.

611 Many approaches have been tried to reduce DUI, including:

- 612 1. Classes for juvenile DUI offenders;
- 613 2. Alcohol abuse treatment as an alternative to license suspensions;
- 614 3. Lowering the legal blood alcohol limit to 0.05;
- 615 4. Introducing random breath testing;
- 616 5. Bar staff training;
- 617 6. Highly publicized sobriety checkpoints;
- 618 7. Underage drinking controls;
- 619 8. Limits on alcohol availability;
- 620 9. Media advocacy; and,
- 621 10. Punishment, including ignition interlock devices or impounding vehicles for  
622 repeat offenders.

623 The first five approaches do not result in a clear pattern of driver response. Some  
624 drivers are frequent violators and appear to need special attention and policies.<sup>(16)</sup>

625 As an example of a more severe approach, DUI laws introduced in California in  
626 1990 included a pre-conviction license suspension on arrested DUI offenders. The  
627 approach was "...highly effective in reducing subsequent accidents and recidivism  
628 among DUI offenders."<sup>(18)</sup>

629 On the other hand, some evidence shows a multipronged approach may be a  
630 more effective choice. "Drinking and driving prevention seems to be most successful  
631 when it engages a broad variety of programs and interventions."<sup>(23)</sup> Such a program  
632 in Salinas, California "...succeeded not only in mobilizing the community, but also in  
633 reducing traffic injuries and impaired driving over a sustained period of time. Traffic  
634 crashes, injuries, and drinking and driving rates all decreased as a result of the  
635 project."<sup>(23)</sup> Programs that concentrated only on sobriety checkpoints appear to  
636 reduce accident frequency and increase DUI arrests over the short-term, but are not  
637 successful over the longer term.<sup>(23)</sup>

638 These DUI approaches suggest that road-use culture can be modified, but that  
639 change requires concentrated legislation and enforcement efforts, as well as  
640 appropriate community programs, to achieve long-term and sustainable results.

641 **A.4.1.8 Conduct Enforcement to Increase Seat Belt and Helmet Use**

642 The effectiveness of enforcing seat belt and helmet use is directly related to  
643 whether or not the laws are primary or secondary laws. A primary seat belt law  
644 allows law enforcement officials to ticket anyone not wearing a seat belt. A secondary

645 seat belt law means that a police officer can only write a ticket for a seat belt violation  
646 if the driver is also cited for some other violation. If a seat belt law is secondary, not  
647 wearing a seat belt is still against the law; however, enforcement of the law is not as  
648 effective.

649 The adoption of primary laws is likely to increase seat belt and helmet use and to  
650 modify road-use culture. Primary enforcement may also lead to an increase in seat  
651 belt and helmet use.

652 A change from secondary to primary seat belt use laws has been shown to  
653 increase seat belt usage and to decrease driver fatalities.<sup>(10)</sup> Most jurisdictions have  
654 supported a change in law with enforcement campaigns. It appears that people are  
655 more likely to wear seat belts after legislation.<sup>(22)</sup> "States in which motorists can be  
656 stopped solely for belt nonuse had a combined use rate of 85 percent in 2006,  
657 compared to 74 percent in other States."<sup>(7)</sup>

658 Similarly, universal helmet requirements for motorcyclists increase helmet use.  
659 In June 2006, 68% of motorcyclists wore helmets that complied with federal safety  
660 regulations in states with universal helmet laws, compared to 37% in states without a  
661 universal helmet law.<sup>(6)</sup>

#### 662 **A.4.1.9 Implement Network-Wide Engineering Consistency**

663 Network-wide engineering consistency refers to the degree to which a  
664 jurisdiction implements transportation engineering solutions using consistent  
665 principles and criteria to design transportation infrastructure and to control traffic.  
666 Consistently and uniformly applying regulatory, warning, and informational signs is  
667 one example. Another example is applying consistent and uniform pavement  
668 markings.

669 The consistency of engineering measures at individual locations and across a  
670 jurisdiction's transportation network is likely to affect the driving habits and road-  
671 use culture of local users. Road users come to expect certain procedures and to act  
672 accordingly. Examples include all-red phases at traffic signals, right-turn-on-red, the  
673 use of left-turn arrows or flashing lights at traffic signals, and policies regarding  
674 yielding to other vehicles and non-motorized travelers at intersections and  
675 roundabouts.

676 When procedures are not consistent across the jurisdiction, safety may  
677 deteriorate. This effect is shown when drivers traveling in a foreign country  
678 encounter different rules of the road.

#### 679 **A.4.1.10 Conduct Public Education Campaigns**

680 Public education campaigns include efforts to educate the public with regards to  
681 new traffic control devices, general rules of the road, and similar topics.

682 Enforcement efforts can include public information, warnings, or educational  
683 campaigns. Such campaigns "...contribute significantly to the effectiveness of the  
684 technology..." used in enforcement, "...result in safer driving habits...", and can  
685 improve the image of police enforcement activities.<sup>(20)</sup> Extensive pedestrian safety  
686 education programs directed at children in elementary schools and those ages 4 to 7  
687 appear to reduce child pedestrian crashes.<sup>(4)</sup>

688 It is also recognized that not all public information and education (PI&E)  
689 programs are effective. A review of some PI&E programs found that the only  
690 programs that resulted in a substantial reduction in speed, speeding, crashes, or crash  
691 severity were those that were integrated with a law enforcement program.<sup>(20)</sup>

692 “General assessment of public information programs has shown [PI&E programs] to  
693 have limited effect on actual behavior except when they are paired with  
694 enforcement.”<sup>(14)</sup>

695 Program effectiveness generally depends on the use of multimedia, careful  
696 planning, and professional production. The impact, however, is difficult to measure  
697 and extremely difficult to separate from the effects of a campaign’s enforcement  
698 component.<sup>(14)</sup>

#### 699 **A.4.1.11 Implement Young Driver and Graduated Driver Licensing Programs**

700 Graduated driver licensing (GDL) programs developed for novice drivers have  
701 been implemented in many jurisdictions. GDL programs typically include restrictions  
702 such as zero blood alcohol, not driving on high-speed highways, not driving at night,  
703 and limitations on the number and age of passengers. The restrictions are designed to  
704 encourage new drivers to gain experience under conditions that minimize exposure  
705 to risk and to ensure drivers are exposed to more demanding driving situations only  
706 when they have enough experience.<sup>(13)</sup> The concern is new drivers are at risk while  
707 getting the experience they need.

708 Novice drivers are three times more likely to be involved in a fatal traffic crash  
709 than other drivers.<sup>(1,24)</sup> Evidence also indicates that the most dangerous times and  
710 situations for drivers aged 16 to 20 years are:<sup>(1)</sup>

- 711     ▪ At night
- 712     ▪ On freeways
- 713     ▪ Driving with passengers

714 The level of risk for young drivers suggests that novice drivers need a learning  
715 period when they are subject to measures that “...minimize their exposure, especially  
716 in known risky circumstances like nighttime and on freeways.”<sup>(1)</sup>

717 Although GDL programs and their results vary, it appears that there is a  
718 decrease in accident frequency with a GDL program.<sup>(13)</sup> There is also an indication  
719 that “increased driving experience is somewhat more important than increased age in  
720 reducing accidents among young novice” drivers.<sup>(13)</sup>

### 721 **A.5 TREATMENTS WITH UNKNOWN CRASH EFFECTS**

722 No information about the crash effects of the following treatments was available  
723 for this edition of the HSM.

#### 724 **A.5.1 Network Traffic Control and Operational Elements**

- 725     ▪ Implement network-wide or area-wide turn restrictions

#### 726 **A.5.2 Road-Use Culture Network Considerations**

- 727     ▪ Install enforcement notification signs
- 728     ▪ Conduce enforcement to reduce red-light running
- 729     ▪ Mitigate aggressive driving through engineering



- 730      ■ Implement older driver education and testing programs

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